

$$a = (6,1 - 1,2 \cdot t) \text{ m/s}^2$$

$$a = \frac{dU}{dt} \Rightarrow dU = a \cdot dt \Rightarrow$$

$$\int_{U_1}^{U_2} dU = \int_{t_1}^{t_2} a \cdot dt \Rightarrow$$

$$U_2 - U_1 = \int_{t_1}^{t_2} a \cdot dt \Rightarrow$$

για $t=0$ s
 $U_0 = 2,7 \text{ m/s}$
 $x_0 = 7,3 \text{ m}$

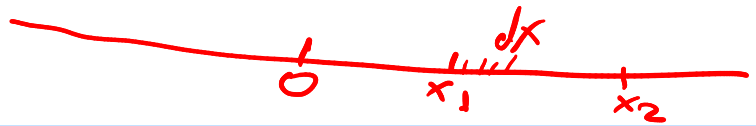
$$* U - U_0 = \int_0^t a \cdot dt \Rightarrow$$

$$U - 2,7 = \int_0^t (6,1 - 1,2 \cdot t) dt \Rightarrow$$

$$U - 2,7 = \int_0^t 6,1 \cdot dt - \int_0^t 1,2 t \cdot dt \Rightarrow$$

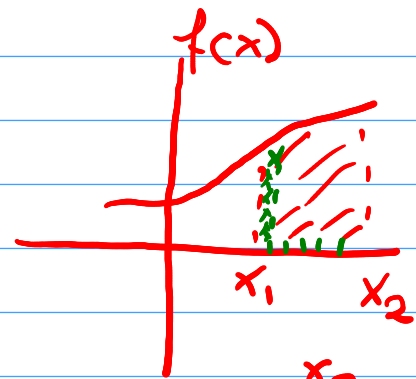
$$U - 2,7 = 6,1 \int_0^t dt - 1,2 \int_0^t t dt \Rightarrow$$

$$U - 2,7 = 6,1 \cdot t \Big|_0^t - 1,2 \frac{t^2}{2} \Big|_0^t$$



$$\int_{x_1}^{x_2} dx = x \Big|_{x_1}^{x_2}$$

$$= x_2 - x_1$$



$$\int_{x_1}^{x_2} f(x) dx$$

$$v - 2,7 = 6,1(t-0) - 0,6(t^2 - 0^2)$$

$$v(t) = -0,6t^2 + 6,1t + 2,7 \quad (\text{m/s})$$

$$t=0 \rightsquigarrow v(0) = 2,7 \text{ m/s}$$

$$t=6 \rightsquigarrow v(6) = -0,6 \cdot 6^2 + 6,1 \cdot 6 + 2,7 \\ = \dots \text{ m/s}$$

$$v = \frac{dx}{dt}$$

⋮

$$v(t) = 0 \Rightarrow -0,6t^2 + 6,1t + 2,7$$

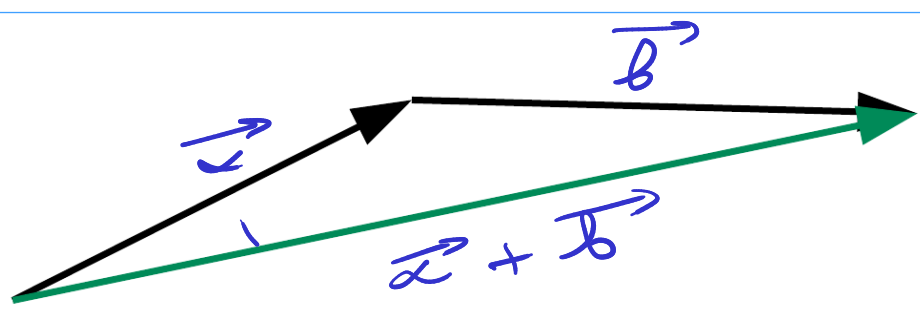
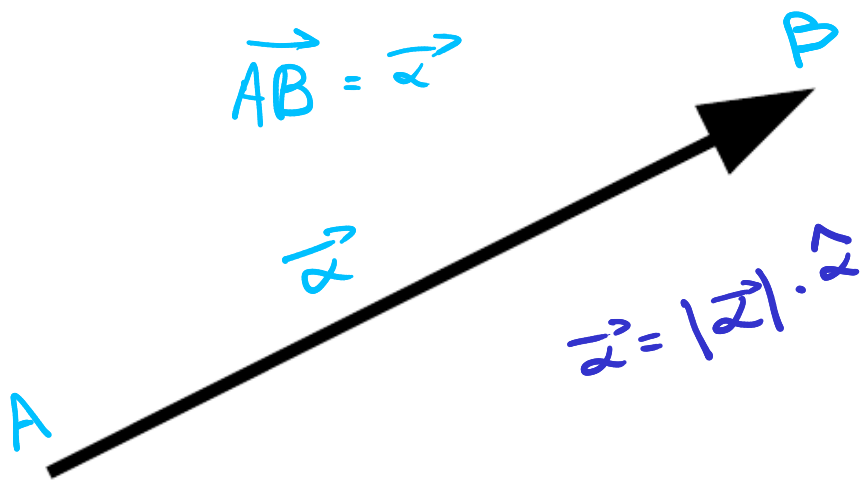
$$\Delta = b^2 - 4ac \Rightarrow \Delta = 6,1^2 - 4(-0,6) \cdot 2,7 \Rightarrow$$

$$\Delta = 37,21 + 6,48 \Rightarrow \Delta = 43,69 > 0$$

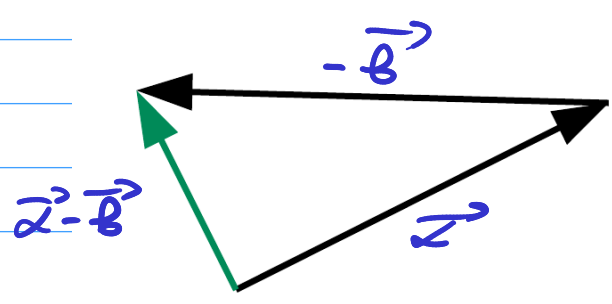
$$t_{1,2} = \frac{-b \pm \sqrt{\Delta}}{2a} \quad \left\{ \begin{array}{l} t_1 = \frac{-6,1 + \sqrt{43,69}}{2(-0,6)} \\ t_2 = \underline{\quad} \end{array} \right.$$

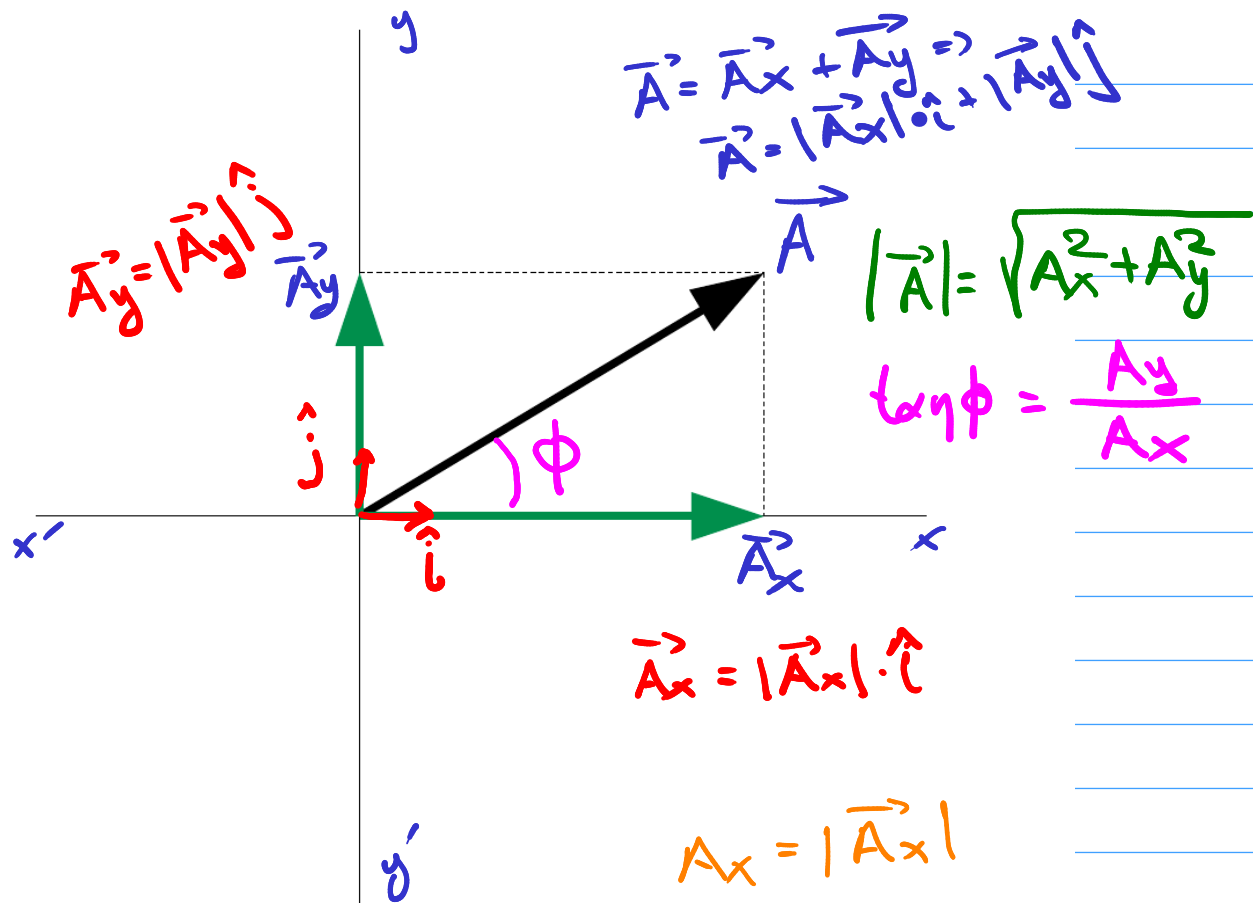
$$t_1 = \frac{0,5}{-1,2} \text{ s.}$$

$$t_2 = \frac{-6,1 - 6,5}{-1,2} = \frac{12,7}{1,2} > 6 \text{ s}$$



$$\vec{a} - \vec{b} = \vec{a} + (-\vec{b})$$





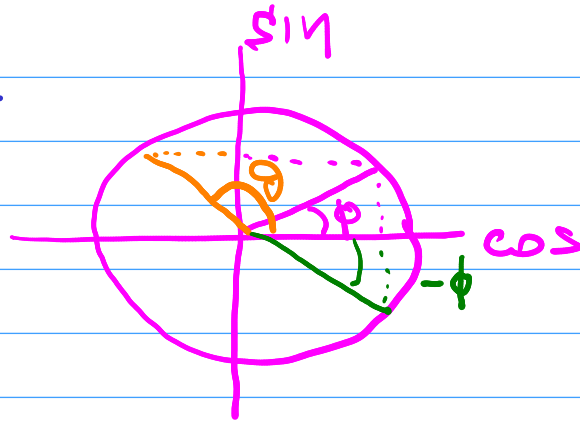
Errow $\vec{A} = A_x \cdot \hat{i} + A_y \hat{j}$
 $\vec{B} = B_x \cdot \hat{i} + B_y \hat{j}$

$$\vec{C} = \vec{A} + \vec{B} = (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$$

$$= (A_x + B_x) \hat{i} + (A_y + B_y) \hat{j}$$

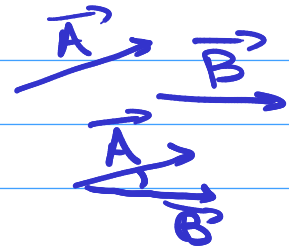
$$\vec{D} = \vec{A} - \vec{B} = (A_x - B_x) \hat{i} + (A_y - B_y) \hat{j}$$

$$\tan \phi = \frac{\sin \phi}{\cos \phi}$$



$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k} \quad \vec{A} = (A_x, A_y, A_z)$$

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \phi$$



$$\vec{A} \cdot \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot$$

$$\cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) =$$

$$A_x B_x \hat{i} \cdot \hat{i} + A_x B_y \hat{i} \cdot \hat{j} + A_x B_z \hat{i} \cdot \hat{k}$$

$$+ A_y B_x \hat{j} \cdot \hat{i} + A_y B_y \hat{j} \cdot \hat{j} + A_y B_z \hat{j} \cdot \hat{k}$$

$$+ A_z B_x \hat{k} \cdot \hat{i} + A_z B_y \hat{k} \cdot \hat{j} + A_z B_z \hat{k} \cdot \hat{k}$$

$$(\hat{i} \cdot \hat{i} = 1 \cdot 1 \cdot \cos 0 = 1 = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k})$$

$$(\hat{i} \cdot \hat{j} = 1 \cdot 1 \cdot \cos 90^\circ = 0 = \hat{i} \cdot \hat{k} = \hat{j} \cdot \hat{k})$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$|\vec{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

$$|\vec{B}| = \sqrt{B_x^2 + B_y^2 + B_z^2}$$

$$\vec{A} \cdot \vec{B} = |\vec{A}| \cdot |\vec{B}| \cos \phi \Rightarrow$$

$$\cos \phi = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|}$$

Πρότυπα

$$\vec{a} \cdot \vec{a} \geq 0$$

$$\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$

$$\vec{a} \cdot (\vec{b} + \vec{c}) = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$$

$$k(\vec{a} \cdot \vec{b}) = (k\vec{a}) \cdot \vec{b} = \vec{a} \cdot (k\vec{b})$$

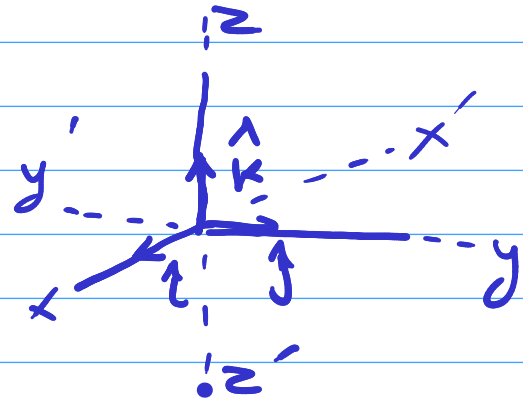
$$\begin{aligned} \vec{a} \cdot \vec{a} &= |\vec{a}| \cdot |\vec{a}| \cos 0 \\ &= |\vec{a}|^2 = \end{aligned}$$

Εξωτερικό γινόμενο

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$|\vec{A} \times \vec{B}| = |\vec{A}| \cdot |\vec{B}| \cdot \sin \phi$$



$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} =$$

$$\begin{vmatrix} + & - & + \\ - & + & - \\ + & - & + \end{vmatrix}$$

$$= \begin{vmatrix} A_y & A_z \\ B_y & B_z \end{vmatrix} \hat{i} - \begin{vmatrix} A_x & A_z \\ B_x & B_z \end{vmatrix} \hat{j} + \begin{vmatrix} A_x & A_y \\ B_x & B_y \end{vmatrix} \hat{k}$$

$$= (A_y B_z - B_y A_z) \hat{i}$$

$$- (A_x B_z - B_x A_z) \hat{j}$$

$$+ (A_x B_y - B_x A_y) \hat{k}$$

$$\vec{B} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ B_x & B_y & B_z \\ A_x & A_y & A_z \end{vmatrix} =$$

$$= \begin{vmatrix} B_y & B_z \\ A_y & A_z \end{vmatrix} \hat{i} - \begin{vmatrix} B_x & B_z \\ A_x & A_z \end{vmatrix} \hat{j} + \begin{vmatrix} B_x & B_y \\ A_x & A_y \end{vmatrix} \hat{k}$$

$$= (B_y A_z - A_y B_z) \hat{i} \\ - (B_x A_z - A_x B_z) \hat{j} \\ + (B_x A_y - A_x B_y) \hat{k}$$

$$\vec{A} = 8\hat{i} - 2\hat{j} + 3\hat{k}$$

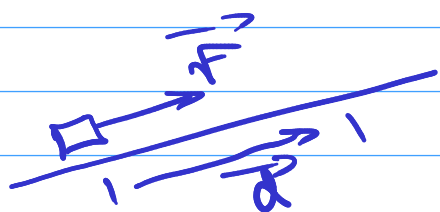
$$\vec{B} = 4\hat{i} + 3\hat{j} - \hat{k}$$

$$\vec{A} \times \vec{B}, \vec{B} \times \vec{A}$$

$$\vec{A} \times \vec{B} = -7\hat{i} + 20\hat{j} + 32\hat{k}$$

$$\vec{B} \times \vec{A} = 7\hat{i} - 20\hat{j} - 32\hat{k}$$

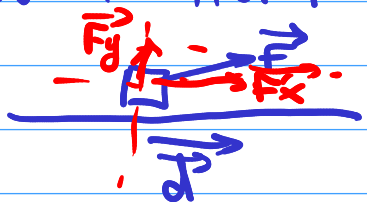
$$\begin{vmatrix} + & - & + & - & + \\ + & - & + & - & + \\ + & - & + & - & + \end{vmatrix}$$



$$\vec{F} = 2\hat{i} + 5\hat{j} + 4\hat{k} \text{ (N)}$$

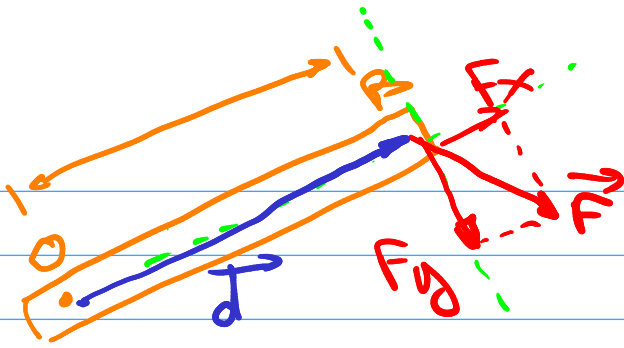
$$\vec{d} = 4\hat{i} + 4\hat{j} + 4\hat{k} \text{ (m)}$$

$$W = |\vec{F}| |\vec{d}| \cdot \cos \phi = \vec{F} \cdot \vec{d}$$



$$W = |\vec{F}| \cdot |\vec{d}| \cdot \frac{\vec{F} \cdot \vec{d}}{|\vec{F}| \cdot |\vec{d}|}$$

$$W = 8 + 20 + 16 = 44 \text{ (J)}$$



$$c = F \cdot d \cdot \sin \phi$$

$$\vec{\tau} = \vec{d} \times \vec{F}$$

$$\vec{d} = 3\hat{i} + 2\hat{j}$$

$$\vec{F} = 5\hat{i} - 4\hat{j} - 2\hat{k}$$

$$\vec{\tau} = ;$$

$$\vec{\tau} = 4\hat{i} - 22\hat{k}$$

$$\vec{\tau} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & 2 & 0 \\ 5 & -4 & -2 \end{vmatrix} = (-4 - (-4) \cdot 0)\hat{i} - (-6)\hat{j} + (-12 - 10)\hat{k} = -4\hat{i} + 6\hat{j} - 22\hat{k} \text{ (N}\cdot\text{m)}$$

$$|\vec{\tau}| = \sqrt{(-4)^2 + 6^2 + (-22)^2}$$

$$= \sqrt{16 + 36 + 484}$$

$$= \sqrt{\quad} = 23,15 \text{ N}\cdot\text{m}$$

$$\sin \phi = ;$$

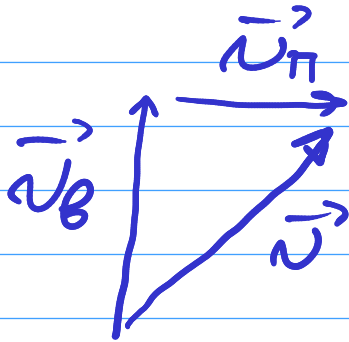
$$\cos \phi = \frac{\vec{F} \cdot \vec{d}}{|\vec{F}| |\vec{d}|}$$

$$\cos \phi = \frac{7}{\sqrt{45} \cdot \sqrt{13}}$$

$$\sin^2 \phi + \cos^2 \phi = 1 \Rightarrow \sin \phi = \pm \sqrt{1 - \cos^2 \phi}$$



$$\vec{u} = \vec{u}_B + \vec{u}_\pi$$



$$\vec{\alpha} \cdot \vec{b}$$

$$\vec{\alpha} \cdot (\vec{b} \cdot \vec{\gamma})$$

$$\vec{\alpha} \times \vec{b}$$

$$\vec{\gamma} (\vec{\alpha} \times \vec{b})$$

$$\vec{\alpha} = \alpha_1 \hat{i} + \alpha_2 \hat{j} + \alpha_3 \hat{k}$$

$$\vec{b} = b_1 \hat{i} + b_2 \hat{j} + b_3 \hat{k}$$

$$\vec{\gamma} = \gamma_1 \hat{i} + \gamma_2 \hat{j} + \gamma_3 \hat{k}$$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$\gamma \vec{a} \times \vec{b} = (\gamma_1 \hat{i} + \gamma_2 \hat{j} + \gamma_3 \hat{k}) \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$= \begin{vmatrix} \gamma_1 & \gamma_2 & \gamma_3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$\vec{a} = 4\hat{i} - 3\hat{j} + 1\hat{k}$$

$$\vec{b} = -1\hat{i} + 1\hat{j} + 4\hat{k}$$

$$\alpha) \vec{a} + \vec{b} \quad \beta) \vec{a} - \vec{b}$$

$$\gamma) \vec{c}; \quad : \quad \vec{a} - \vec{b} + \vec{c} = 0$$

$$\delta) \vec{a} \cdot \vec{b} \quad \epsilon) \vec{a} \times \vec{b}$$

$$\zeta) \vec{c} (\vec{a} \times \vec{b})$$

